

Lyn Buchanan Target tasked by Lyn Buchanan - LB9

Remote viewed by Anita Ikonen - Method EEC

Target Mar 01 , 2006

Today May 13, 2018

Start 5:46 PM

Mar 01 2006

May 13, 2018

Start 5:46 PM. This target is an "event", I read that clue on the page because I want to see the target number (date) and the feedback link (weblink) at the same time because I need both the target number and the feedback link to look at so that reveals the clue that is written in the middle. I would prefer to not have a clue, but here goes it is still millions of possibilities of what it could be.

I see colors from numbers due to synesthesia so Mar 01 has as numbers and letters a very cheerful and bright yellow color like the feeling of spring and Easter decorations such as tulips and yellow chicken decorations but when I feel the target it is dark and gray and not amused and entirely different.

Steel gray color, steel metal surface. This will sound a bit strange, but you know when steel metal surface has been polished by a machine it creates a smooth surface yes but there will also be diagonal lines across the surface which are due to the polishing device, it has that, kind of like a signature polishing mark or signature that happens due to that polishing device exactly, a different polishing device with a different serial number would have given a somewhat different mark on the surface. Because there is this friction when you polish a steel metal surface and it will create an ear piercing sharp sound of polishing the metal as it slowly grinds across the surface. The polishing device is a large like the lid of a shoebox only square shaped and larger, what I mean is that it is like a shoebox with short edges, the "bowl side" of the "lid" is facing so that if you put something into it the contents would fall down out of it.

What I am seeing is the polishing device, it is large square shaped meaning all four sides are of equal length. One length is about an arm's length or more. This is (and I need to get better at describing objects in words, that is a fun exercise to develop better skills at how to describe an object well, also the drawing helps) this is, or it has, a flat surface parallel to the horizontal plane, and from all four sides at their edges runs an edge downward a bit only a few centimeters perhaps five centimeters wide or downward, this is how this polishing device looks like the lid of a shoebox which is oriented exactly like if you just now opened a shoebox then the short edges are reaching downward.

Above the flat plane of the device is a metal pipe which is darker dark steel grey in color and it is attached to the device above it and this pipe runs also along the horizontal plane but slightly

above the device, this pipe makes a 90 degree angle more than once, in its arrangement above the "shoebox lid" shaped device. What this pipe does is that this "lid" is moved mechanically by a robot arm and this pipe is what enables the movement and so we assume that this pipe has got joints of some sort.

This lid will move across a large sheet of steel that is beneath it, and this lid polishes the steel sheet and the exact make of this "lid" device produces in the polished steel a unique signature mark of diagonal grooves or lines which are inevitable and which are unique for each particular polishing device unit, one could then therefore study those grooves or etches to determine which particular polishing device unit has been used in its manufacture. This works on the same principle as when a bullet is fired through a gun and a forensics expert can study the exact grooves that become etched on the fired bullet, in order to determine which exact gun unit was used to fire that bullet, that is the exact same principle at work here.

Now the polishing device, which I have also called the "shoebox lid" due to the similar appearance, it will move quickly and swiftly without hesitation, since it is being operated by a robot that makes it move. Important to know about the movement of the pipe, which then causes the movement of the "shoebox lid" polishing device, is that there are no rounded or graceful ballerina moves, imagine an ice skater woman who can make nice rounded curves on the ice with the skates on the ice, however this machine can only go in exactly square shaped trajectories, so it is like an etch a sketch. The robot can steer the device through the pipe setup to go in the y-direction and in the x-direction (if we imagine this as on a graph in calculus mathematics) but it can make no parabolic smooth running curves of the trajectory. It can make any kind of short stepwise motions to *mimic* a diagonal path but it is then stepwise building the path of like a staircase because it needs to make sharp angles at each turn.

The robot itself which operates the movement of the polishing device, it cannot be operated by a human in the navigation control, because the movements follow a very robotic movement in which it is clear just by seeing the way that the device is moved that a human would not be steering it so robotically, so confidently, so quickly. A human would require a bit more of time in between each angle and the pacing of each path would also show slight differences, whereas here each path line trajectory is done with equal precision and pace. Were it a human mind steering it with controls then the pace of individual steps would reveal small differences.

There is a steel object that has the diagonal shine grooves that come due to when it was polished by the machine.

On the drawing you can see the steel sheet on the bottom and the shoebox lid polishing device and the dark metal pipe which moves the lid from above. Notice that the drawing does not present how the lid is not a solid block: remember that the lid has a hollow space underneath it and that it has no bottom! It is only one sheet, which you see, and then the short edges like on a

shoebox. It is like a shoebox lid only larger and square.

The polishing device moves *slightly above* the surface of the steel sheet.

All of this info so far just came right at me very quickly. I will now look at the numbers this was all from a first glance at the target number and feedback link on the page.

There is a man here who is not amused and he is being rather serious. He is an old man. There is nothing angry about him, so he is serious but not in a negative or aggressive manner.

Everything is steel colored and gray about this target.

6:19 PM Pause.

6:54 PM Resume.

So what we have is an interesting target. We have a machine.

So I have described my initial information. I am still learning how to do RV successfully. I know by now that more than likely, my initial information up to this point will be accurate. As I proceed from here there is an elevated risk of the evolution of a false story, I know that from past experience with targets that I am now standing on the point from which I either go in the right direction with more accurate information, or I start building a false story.

A false story seems to be characterised by being a long story which goes in one direction only, on the other hand I see that when I am reporting accurate information I will be going back and forwards with repeated descriptions of *elements*. With a false story it will go forward in a line progression and it will have a story and it will also tend to ignore or forget entirely about the initial elements. I do not recall the statistics of it, but perhaps also that a false story *will not contain* the initial accurate elements at all.

So, I know from experience that I must maintain the initial elements, which are the steel sheet, polishing device, pipe system, and the serious old man. I will look at these elements more closely. The previous information up to this point was the automatic accurate and fun part. Now I go to the effort part, the effort part has a risk of producing inaccurate information, or it could also produce accurate information, but I have to figure out how to RV successfully in this effort stage.

The steel has been polished, it has been polished by a polishing device. And the old man is looking at it, he is inspecting the surface, he places his eyes level to the sheet and has his hands on the steel by the fingertips.

Serious gray steel with those diagonal groove lines that were etched into it by the industrial process of polishing the steel sheet. The man is a surveyor. There is nothing lively going on here. An industrial site. A pipe that is lifted on a crane. The crane hoists it up and places it into the

correct position. The pipes are being placed, they are building something. The steel was being cut earlier, into those right sized sheets.

This is risky as it can produce a false story perhaps, I need to keep track of the statistics from now on and study the RV accuracies. I am about to do an exploration, which means I pretend that I go to the target location in person to see and interact with the site. I want to keep track from now on whether explorations involve a high risk of inaccuracy or whether exploration is fairly reliable. I decide also in this target and perhaps for several of the subsequent targets, that an exploration is only done on the initial elements, as initial elements are reliable. Exploration done on elements found in the effort stage could pose an elevated risk of inaccurate information perhaps. So, I will do exploration only on initial stage elements. I go to the steel sheet.

Something goes warm here, and something goes up here. They are hoisting the steel sheet high up! It is being lifted up by a crane, they are hoisting it up it goes up lightly as if it weighs almost nothing, there is no heavy weight pressing down on the steel sheet. Aha, the shoebox could even be a magnet that lifts up metal, I don't know that is just a logical thought so that is not valid as I did not RV the magnet as being an element.

Exploration of steel sheet: It was lifted up. It rocked slowly or actually tilted slowly from side to side as it was slowly being lifted up. The steel sheet feels weightless and effortless it has no heavy weights on it.

The steel sheet is an initial element and therefore credible. Look underneath the steel sheet: It is dark there underneath it, and there seems to be nothing there.

Method of "do what the man does": I am watching all of this work take place. It all needs to be laid down accurately. I am a strong man and I am reliable at this place, I would step in if something were about to go awry. I would stop the machines immediately. There is a stop button to press and the machine would stop.

Investigate the crane and robot that makes the movement: Tall, light weight, thin parts that lean diagonally toward one another with contact up top, I will draw it. Orange color.

Logic sets in now, logic is telling me "what if I am wrong?". So I tell to logic, "so what if I am wrong, the task is to record my impressions, if the impressions are wrong then that does not matter, the impressions will be judged for accuracy and there is no personal or emotional investment, it is an impersonal process".

The man is not going to get sleepy. He has to watch all this closely and there is no time to get sleepy eyed. He watches with his eyes closely with eyes level to the steel sheet and his hands are wide to his sides with bent elbows and his fingertips are pressed against the steel sheet.

Taste the steel sheet: It tastes like charcoal.

Stand on the steel sheet: I can't, because it starts moving, it is slowly being lifted.

Look at the target site from above: Many things, components for building, building materials, were being shipped to this site from up to the right, diagonally up and right, in the drawing. These materials came in sets of several of the same kind of sets together.

What are they building, what will it be used for: It is just being watched for now. The steel gray is being watched now.

Watch the steel gray yourself: I am watching the surface, and at exactly how it is being prepared.

The steel sheet goes up! It is being lifted up! It has a reflectiveness almost like a pane of glass but glass would have been more heavy for its size. It is hoisted up and then slowly moved by the crane to the left, the sheet is attached by three gray metal wires as drawn, to the sheet, and the sheet tilts slowly from side to side as it rocks as it is being moved by the crane.

What is the next step in the RV now?

A method which I here for the first time title as "digging". Digging means in this case that I look at the target link on the page (without clicking it of course) and I "grab at" the energy there which is the information, this uses effort. It is a way of my mind's focus "grabbing" at the energy of the things there and causing a "touching" and an "interaction". Initial elements come in a subtle way, and "digging" gets information by effort and by causing an impact on the information, digging is more violent or impactful in a way.

There is a gray steel colored metal box and it sits there. It has been cut like cut steel. It is a serious industrial box.

Go inside the box: It has parts that are the dark gray "pipe setup", these are rigid dark metal pipes which can be bent to create movement.

So we are dealing with a steel box which has pipes or cranks that can bend at "elbows" in the pipe setup to cause a robotic device to move spatially. This movement by the pipes occurs only along the horizontal plane by the way! And the movement is otherwise as earlier described.

Alright so let's look at the clue. Even with the clue the target could be any out of millions of things so it should not feel like cheating. An event. I therefore ask myself "what is happening at this target?". Well I have nothing more to add to what was already described.

I feel into the target feedback link. It is yellow and brightly lit there, in amidst all the steel color and the steel colored box is there. I hear the screeching sound of when a sheet of steel had been cut

by the polishing device. I add the yellow color to the drawing.

7:28 PM. I am going to conclude here and click on the target map. No first let me try to see the area. Not sure. I click on the map. The target map is an illustration of the entire United States.

I will click on the target feedback link and judge this RV based on its correlation to the target. I have no title for this RV as I cannot say what I think this target is by one or a few words, so we only have the description.

The target is "trying to ride a bull". The fence definitely provides the element of the moving steel pipes although they are painted white but are probably gray steel inside. I can accept the man who was monitoring as being possibly relevant to the target. I did not detect the bull animal.

What about the steel sheet? Well they do lift a person down onto a bull and then they would open the gates but there is no crane used and I do not see any steel sheet.

If my RV is correct then this event is serious and technical and industrial and robotic where they use precision and skill and focus and lots of surveying and making sure that everything is going right. I did not see a human or a bull to be moving. The crane is probably not there.

The mood from the old man who is surveying could be right. The pipes could be the steel gate moving as that is one of the central events that are part of the main event. Riding a bull consists of sitting down on the bull (crane lifting something into position?), the gate being opened (the pipe setup moving the steel sheet?). Possibly I got some elements of the target but overall a remote viewing would be expected to describe this target differently.

I grade this RV a C.

Mar 01, 2006

060301/_____

ELEMENTS LISTING

Horizontal plane of steel sheet which as diagonal lines or grooves etched into it due to the polishing by a polishing device which caused a unique signature mark of polished etches which could be used to identify the exact polishing device unit which had been used. A crane lifted up the steel sheet.

Polishing device which moves robotically across the sheet and polishes the sheet and causes inadvertently its unique diagonal grooves on the surface. See a more detailed description above.

Dark gray steel metal pipe system which is attached to the polishing device above the polishing device, the pipe system is apart from the point of attachment to the polishing device, a bit above

the polishing device so to not cause friction or rubbing against the top of the polishing device as the robot moves this machine. The pipe is used to move the polishing device across the steel surface.

A man, old man, serious but not in an aggressive or negative way.

Crane that hoists industrial components high up. Something industrial and steel is being built here.